

1. **Nonlinear Equations** Given scalar equation $f(x) = 0$

- a. describe the convergence of the root-finding algorithm.
- a sufficient condition for convergence is established a priori
- the root-finding algorithm or the convergence of the root-finding algorithm.
- d. describe the algorithm as a fixed point iteration. • a sufficient condition for a general fixed point iteration to converge.
- e. the convergence of the fixed point iteration of the root-finding algorithm and develop an alternative root-finding algorithm.

Solution

a. Newton's method Given x_0 let

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad n = 0.$$

• the convergence of Newton's method Given x_0, x_1 let

$$x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})} \quad n = 1.$$

Newton's method of $f(x) = 0$. Suppose there is an interval $E = [a, b]$ such that $f(a) \cdot f(b) < 0$ and $f'(x)$ are continuous on E and

$$\max_{x \in E} \frac{|f(x)|}{|f'(x)|} = M,$$

and $M < 1.0$. Then for any $x_0 \in E$ Newton's method will converge in at most 2.0.

• the convergence of the secant method Suppose x_0 and x_1 are in E and the convergence of the secant method will converge in at most $\frac{1+\sqrt{5}}{2} \approx 1.62$.

• see the problem set 5, 60.

d. define

$$g(x) = x - \frac{f(x)}{f'(x)}.$$

Ne on s¹ e od an e as as Given x

Numerical quadrature:

2. Assume that a quadrature rule, when discretizing with n nodes, possesses an error expansion of the form

$$I - I_n = \frac{c_1}{n} + \frac{c_2}{n^2} + \frac{c_3}{n^3} + \dots$$

Assume also that we, for a certain value of n , have numerically evaluated I_n , I_{2n} and I_{3n} .

- Derive the best approximation that you can for the true value I of the integral.
- The error in this approximation will be of the form $O(n^{-p})$ for a certain value of p . What is this value for p ?

Solution:

- With three numerically evaluated values, we can solve for three variables. For these we want to choose I , c_1 and c_2 , at which point we only care about the obtained value for I . Abbreviating $\frac{c_1}{n} = d_1$ and $\frac{c_2}{n^2} = d_2$, we thus obtain the relations

$$\begin{aligned} I - I_n &= d_1 + d_2 \\ I - I_{2n} &= \frac{1}{2}d_1 + \frac{1}{4}d_2 \\ I - I_{3n} &= \frac{1}{3}d_1 + \frac{1}{9}d_2 \end{aligned} ,$$

or, written in the usual linear system form (separating 'knowns' from 'unknowns')

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & -\frac{1}{2} & -\frac{1}{4} \\ 1 & -\frac{1}{3} & -\frac{1}{9} \end{bmatrix} \begin{bmatrix} I \\ d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} I_n \\ I_{2n} \\ I_{3n} \end{bmatrix}$$

from which follows

$$I = \frac{1}{2}(I_n - 8I_{2n} + 9I_{3n}).$$

- With the first two terms in the error expansion eliminated, it will continue from the third term and onwards (with modified coefficients), i.e. the error in the approximation above will be of the form $O(n^{-3})$.

4. Linear Algebra

Consider the $n \times n$ nonsingular matrix A . The Frobenius norm of A is given by

$$\|A\|_F = \sqrt{\sum_{i,j} a_{ij}^2}$$

Consider the relation $\|A\|_F = \sqrt{\text{tr}(A^T A)}$. All Frobenius norms satisfy $\|A - B\|_F$ is a seminorm in the sense that it is a norm on the space of symmetric matrices.

clearly

$$A - A U \Sigma^{-1} V$$

is singular.

Let u_1, u_2, \dots, u_n and v_1, v_2, \dots, v_n be a basis for U and V respectively. Then $U = \sum_{j=1}^n u_j u_j^T$ and $V = \sum_{j=1}^n v_j v_j^T$.

$$A = \sum_{j=1}^n u_j v_j^T$$

and the Frobenius norm is

$$\|A\|_F^2 = \sum_{j=1}^n \sum_{k=1}^n u_{jk}^2 v_{jk}^2 = \sum_{j=1}^n \|u_j\|_2^2 \|v_j\|_2^2$$

or

$$\|A\|_F^2 = \sum_{j=1}^n \|u_j\|_2^2 \|v_j\|_2^2$$

Since A is any matrix, $A - A U \Sigma^{-1} V$ is singular. Hence there is a vector w such that

$$A w = 0.$$

No

$$\min_{\|z\|=1} \|Az\| = \min_{\|w\|=1} \|Aw\|$$

is the singular value of A . Since A is real and symmetric, the singular values are the absolute values of the eigenvalues. Hence the Frobenius norm is

$$\|A\|_F^2 = \sum_{i=1}^n \lambda_i^2$$

is

$$\|A\|_F^2 = \sum_{i=1}^n \lambda_i^2$$

Let $\lambda_1, \lambda_2, \dots, \lambda_n$ be the eigenvalues of A . Then A is invertible if and only if $\lambda_i \neq 0$ for all i . In this case, the inverse of A is given by $A^{-1} = \sum_{i=1}^n \frac{1}{\lambda_i} u_i u_i^T$. The Frobenius norm of A^{-1} is $\|A^{-1}\|_F^2 = \sum_{i=1}^n \frac{1}{\lambda_i^2}$.

Numerical ODE:

5. Consider using forward Euler (same as AB1; Adams-Bashforth of first order) as a predictor, and the trapezoidal rule (same as AM2; Adams Moulton of second order) as a corrector for solving the ODE $y' = f(t, y)$.
 - a. Write down the explicit steps that need to be taken in order to advance the numerical solution from time t_n to time $t_{n+1} = t_n + k$.
 - b. Determine the order of the combined scheme. In case you know a theorem that gives the order directly, you may quote this *in its general form*, i.e. do not just state the answer in the present special case.
 - c. The figure to the right illustrates the stability domain of the scheme. Prove that $(-2, 0)$ is the leftmost point

6. Partial Differential Equations

Consider the steady state advection-diffusion equation in one space dimension

$$- \epsilon u_{xx} + a u_x = b u - f, \quad x \in (0, 1)$$

with boundary conditions $u(0) = u(1) = 0$ and the assumption that $a > 0$ is constant and $\epsilon > 0$ or $x \in (0, 1)$

are prescribed. The differential equation is linear in u and the boundary conditions are homogeneous. The right-hand side f is prescribed. The linear system $A u = b$ and A is a tridiagonal matrix.

Assume $a > 0$ and $b > 0$ are constants. The relationship between a , b and h is assumed to be $a > b > 0$ and $h < 1$. The eigenvalues of A are real and positive.

For constants $a > 0$, $b > 0$ the Gerschgorin conditions on the eigenvalues of A are **upwind** direction.

Now consider the parabolic equation assuming $a > 0$ and $b > 0$ are constants

$$u_t - \epsilon u_{xx} + a u_x = b u - f, \quad x \in (0, 1)$$

where the **Forward** method is used for the advection term.

Reference: [1] G. I. Bell, *Journal of Computational Physics*, 1984, 53, 1-16. doi:10.1016/0021-9991(84)90001-0

ere $i = X_{-1}, X_{+1}$.

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$$b_X \frac{-u_{X-1} - u_{X+1}}{2h} = b_X u_X - \frac{h^2}{12} b_X u^{(3)},$$

ere $i = X_{-1}, X_{+1}$.

e ind i eren es en il $_{\xi}$ or e se ond ξ is ξ or $b_X > 0$

$$b_X \frac{-u_{X-1} - u_X}{h} = b_X u_X - \frac{h}{2} b_X u,$$

ere $i = X_{-1}, X$ and ξ or $b_X < 0$

$$b_X \frac{-u_X - u_{X+1}}{h} = b_X u_X - \frac{h}{2} b_X u,$$

ere $i = X, X_{+1}$.

i en ered di eren es e linear sys $\mathbf{A} \mathbf{u}$ is ridia onal deno ed y

$$\mathbf{A} = \frac{1}{h^2} \text{tri} \left[-a_X - h/2, \frac{1}{2} b_X \quad a_X - h/2, a_X, h/2 \quad -a_X, h/2 - \frac{h}{2} b_X \right]$$

For \rightarrow indifference and \rightarrow on \mathbb{R}^n if $a >$